

September 2008

Dear Customer

Important Notices

Thank you for your continued patronage of Toshiba microcontrollers.

This page gives you important information on using Toshiba microcontrollers. Please be sure to check each item for proper use of our products.

▶ Caution in Setting the UART Noise Rejection Time (September 2008)

- * If your datasheet is dated 1 July 2008 or earlier, please download the latest datasheet or request it from your local Toshiba office.

▶ Restriction on Use of the Interrupt Controller (March 2006)

- * If your datasheet is dated 28 December 2005 or earlier, please download the latest datasheet or request it from your local Toshiba office.

TOSHIBA Microcontrollers TLCS-870 Family

TLCS-870/X Series

TMP88CH40	TMP88CH40I	TMP88PH40	TMP88CH41	TMP88PH41	TMP88FH41	TMP88CS42
TMP88PS42	TMP88CS43	TMP88FW44	TMP88FW45	TMP88FW45A	TMP88F846	TMP88CH47
TMP88CK48	TMP88CM48	TMP88CS48A	TMP88CK49	TMP88CM49	TMP88C060	

TLCS-870/C Series

TMP86P202	TMP86P203	TMP86CH06	TMP86CH06A	TMP86PH06	TMP86C906	TMP86C407
TMP86C407I	TMP86C407S	TMP86C807	TMP86C807I	TMP86C807S	TMP86F807	TMP86P807
TMP86C408	TMP86C408I	TMP86C408S	TMP86C808	TMP86C808I	TMP86C808S	TMP86F808
TMP86P808	TMP86C908	TMP86C809	TMP86CH09	TMP86F409	TMP86F809	TMP86FH09
TMP86FH09A	TMP86C909	TMP86C912	TMP86CH12	TMP86FH12	TMP86C420	TMP86C820
TMP86P820	TMP86CH21	TMP86CH21A	TMP86C822	TMP86CH22	TMP86PH22	TMP86CP23
TMP86CP23A	TMP86CM23	TMP86CM23A	TMP86FS23	TMP86PM23	TMP86PS23	TMP86C923
TMP86FP24	TMP86CM25	TMP86CM25A	TMP86CS25	TMP86CS25A	TMP86FM25	TMP86PS25
TMP86C925	TMP86FM26	TMP86CM27	TMP86CP27A	TMP86FS27	TMP86PS27	TMP86C927
TMP86CS28	TMP86FS28	TMP86C829	TMP86C829A	TMP86C829B	TMP86CH29	TMP86CH29A
TMP86CH29B	TMP86CM29	TMP86CM29A	TMP86CM29B	TMP86CM29L	TMP86FM29	TMP86PM29
TMP86PM29A	TMP86PM29B	TMP86C929A	TMP86CS41	TMP86CS43	TMP86CS44	TMP86PS44
TMP86C944	TMP86C845	TMP86C846	TMP86CH46A	TMP86CM46A	TMP86FH46	TMP86FH46A
TMP86PH46	TMP86PM46	TMP86C847	TMP86C847I	TMP86C847S	TMP86CH47A	TMP86CH47I
TMP86CH47S	TMP86CM47A	TMP86FH47	TMP86FH47A	TMP86PH47	TMP86PM47	TMP86PM47A
TMP86C947	TMP86FM48	TMP86C948	TMP86CH49	TMP86CM49	TMP86CS49	TMP86FS49
TMP86FS49	TMP86FS49AI	TMP86FS49B	TMP86PM49	TMP86C949	TMP86CS64	TMP86CS64A
TMP86FS64	TMP86PS64	TMP86C964	TMP86CH72	TMP86CM72	TMP86PM72	TMP86C972
TMP86CK74A	TMP86CM74A	TMP86PM74A	TMP86C974	TMP86CM87R	TMP86CM87R	TMP86PM87R
TMP86C987	TMP86C989	TMP86CH92I	TMP86CH92S	TMP86FH92	TMP86FH92I	TMP86FH93
TMP86C993						

TLCS-870 Series

TMP87CH29	TMP87CK29	TMP87CM29	TMP87PM29	TMP87CH48	TMP87CH48I	TMP87CM48
TMP87PH48	TMP87PM48	TMP87CM53	TMP87PM53	TMP87CS68	TMP87PS68	

*Applicable products include all TLCS-870 Family microcontrollers with the UART function including custom products and products supplied as bare chips that are not listed above. If you have any questions, please contact your local Toshiba sales representative.

September 2008

Caution in Setting the UART Noise Rejection Time

With regard to the TLCS-870, TLCS-870/X and TLCS-870/C Series of Toshiba's 8-bit microcontrollers listed above, please be informed that certain combinations of transfer clock frequency and noise rejection time should not be used in the UART (asynchronous serial interface) as explained below. If you need further information, please contact your local Toshiba sales representative.

[Applicable Usage Conditions]

This caution applies when the timer/counter interrupt is selected as a transfer clock of the UART and the transfer clock frequency (f_c) and the RXD input noise rejection time are set to one of the combinations shown in the table below. Under any other conditions, the noise rejection can be used without any problem.

Communication mode setting	Transfer clock select	Transfer clock frequency [Hz] (Note)	RXD input noise rejection time setting	f_c frequency [MHz]	Communication speed [bps]
Receive operation (RXE=1)	Timer/counter interrupt (BRG=110)	$f_c/8$	Reject pulses shorter than $31/f_c$ as noise (RXDNC=01)	1.229	9600
				2.458	19200
				4.915	38400
				9.830	76800
		$f_c/16$	Reject pulses shorter than $63/f_c$ as noise (RXDNC=10)	1.229	4800
				2.458	9600
				4.915	19200
				9.830	38400
				19.661	76800
		$f_c/32$	Reject pulses shorter than $127/f_c$ as noise (RXDNC=11)	1.229	2400
				2.458	4800
				4.915	9600
				9.830	19200
				19.661	38400

Note: The transfer clock is calculated by the following equation:

$$\text{Transfer clock [Hz]} = \text{Timer/counter source clock [Hz]} \div \text{TREG set value}$$

[Problem] In receive operation (RXE=1), input data on the RXD pin may not be received properly.

[Workaround] If you are using the UART with one of the above noise rejection time settings, disable the noise rejection or change the noise rejection time to a shorter period.

TOSHIBA Microcontrollers TLCS-870 Family **TLCS-870/C Series**

TMP86C822	TMP86CH22	TMP86PH22		
TMP86CM23/CM23A	TMP86CP23/CP23A	TMP86PM23	TMP86PS23	TMP86FS23
TMP86CM27	TMP86CP27/CP27A	TMP86PS27	TMP86FS27	
TMP86CH49	TMP86CM49	TMP86CS49	TMP86PM49	TMP86FS49/FS49A

Dear Customer

March 2006

Restriction on Use of the Interrupt Controller

This is to inform you of a restriction that has been found with regard to the interrupt controller contained in some of the TLCS-870/C Series microcontrollers. If you need further information, please contact your local Toshiba sales office.

[Phenomenon]

The interrupt latch IL15 (INTADC: AD conversion end interrupt) may be cleared without the interrupt that set the latch being processed.

[Condition]

If an INTADC interrupt request is generated while an interrupt with priority lower than IL15 (INTADC) is being accepted, the interrupt latch for INTADC is cleared immediately after it has been set.

[Restriction]

(1) Workaround not using the AD conversion end interrupt

Whether or not AD conversion is completed can be detected by monitoring the AD conversion end flag (EOCF) by software. This can be done by polling EOCF or monitoring EOCF at regular intervals after start of AD conversion.

(2) Workaround for detecting AD conversion end while a lower-priority interrupt is being processed

While an interrupt with priority lower than INTADC is being processed, check the AD conversion end flag (EOCF) and interrupt latch IL15. If IL15 = 0 and EOCF = 1, call the AD conversion end interrupt processing routine with consideration given to PUSH/POP operations. At this time, if an interrupt request with priority higher than INTADC has been set, the AD conversion end interrupt processing routine will be executed first against the specified priority. If necessary, we recommend that the AD conversion end interrupt processing routine be called after checking whether or not an interrupt request with priority higher than INTADC has been set.