# **Application Note**

# TSPI\_SLAVE\_RECEIVE (TSPI-E)

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### 1. Preface

This application note describes the sample software for TSPI\_SLAVE\_RECEIVE using Serial Peripheral Interface (SPI).

This document helps the user check operation of a product under development and develop its program.

### 2. Technical Term

Term/Abbreviation	Definition	
BSP	Board Support Package	
CG	Clock Control and Operation Mode	
CRC	Cyclic Redundancy Check	
DMA	Direct Memory Access	
Timer	T32A:32-bit Timer Event Counter	
TSPI	TOSHIBA Serial Peripheral Interface	

### **3. Reference Document**

Document	Notes
Data sheet	Refer to the data sheet of MCU to be used.
Reference manual	Refer to the reference manual of each IP to be used.
Application note MCU User Guide	Refer to the MCU user guide to be used.

### 4. Target Sample Program

Sample Program	Outline
TSPI_SLAVE_RECEIVE	Sample program of SPI function (Slave Receive)

## 5. Configuration Diagram



## 6. Sample Program:TSPI\_SLAVE\_RECEIVE

This sample software that uses the Slave receive processing function of the SPI communication function to enter the reception waiting state when the switch is pressed, and switches the LED turn on / turn off each time data receive is completed.

This sample software allows you to select FIFO\_MODE or DMA\_MODE.

#### 6.1. Outlines of Operation

Turns off BSP\_LED\_2, BSP\_LED\_3, and BSP\_LED\_4.

When BSP\_PSW\_1 is pressed, BSP\_LED\_3 and BSP\_LED\_4 are turned off and data for the data size is received. The data that exceeds the data size will be discarded.

Switches the lighting status (turn on / turn off) of BSP\_LED\_2.

When SPI read error occurs, BSP\_LED\_3 is turn on.

When the CRC value of the received data and the calculated CRC value do not match, BSP\_LED\_4 is turn on.

#### 6.2. Function to Use

The functions to use are as follows:

For the Port assignment of each BSP channel, refer to the MCU user guide.

IP	Channel	Objective
TSPI	BSP_TSPI_1	SPI communication
T32A	BSP_T32A_TIMER_1	Interval timer
PORT(Push-Switch)	BSP_PSW_1	Event trigger
	BSP_LED_2	For operation check
PORT(LED)	BSP_LED_3	For operation check
	BSP_LED_4	For operation check

#### 6.3. Interrupt to Use

Interrupt	Outlines	
INTT32A00A	T32A Timer A	
	Timer counter increment every 1ms for Switch processing	
*1	1 SPI receive interrupt	
*2	SPI error interrupt	
INTDMAATC	DMA transmit end interrupt	
INTDMAAERR	DMA error interrupt	
	CODY" for Addus M2HOE10 "INIT1DY"	

\*1 For SBK-M4KN, "INTSCORX", for AdBun-M3HQF10, "INTT1RX"

\*2 For SBK-M4KN, "INTSC0ERR", for AdBun-M3HQF10, "INTT1ERR"

#### 6.4. Configuration

"main.c" configuration setting.

Configuration	Current Value	Description
DATA_LENGTH	14	Data size (Unit: byte)
		Set to 16 by setting the compile switch CHK_CODE
CHK CODE	CHK_CODE_CRC16	CHK_CODE_CRC16 and CHK_CODE_CRC32 can be
•••••		switched
RX_MODE	FIFO_MODE	FIFO_MODE and DMA_MODE can be switched
RX_FILL_LEVEL	4	Receive Fill level setting

#### 6.5. Example of Terminal Emulator Output

Nothing.

## 7. Activity diagram

#### 7.1. main







<sup>\*</sup> In the case of M4KN/MN, n=0; in the case of M3H, n=1











#### 7.2. variable\_initalize



#### 7.3. driver\_initialize



#### 7.4. driver\_finalize



#### 7.5. application\_initialize



#### 7.6. application\_finalize



### 7.7. tspi\_initialize



\* In the case of M4KN/MN, n=0; in the case of M3H, n=1

#### 7.8. sw\_state\_change\_handler



### 7.9. Interrupt







## 8. Revision History

Revision	Date	Description
1.0	2023-10-16	First release

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