

# **Application Note**

# TSPI\_MASTER\_RECEIVE \_(TSPI-E)\_

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### 1. Preface

This application note describes the sample software for TSPI\_MASTER\_RECEIVE using Serial Peripheral Interface (SPI).

This document helps the user check operation of a product under development and develop its program.

## 2. Technical Term

Term/Abbreviation	Definition
BSP	Board Support Package
CG	Clock Control and Operation Mode
CRC	Cyclic Redundancy Check
DMA	Direct Memory Access
Timer	T32A:32-bit Timer Event Counter
TSPI	TOSHIBA Serial Peripheral Interface

### 3. Reference Document

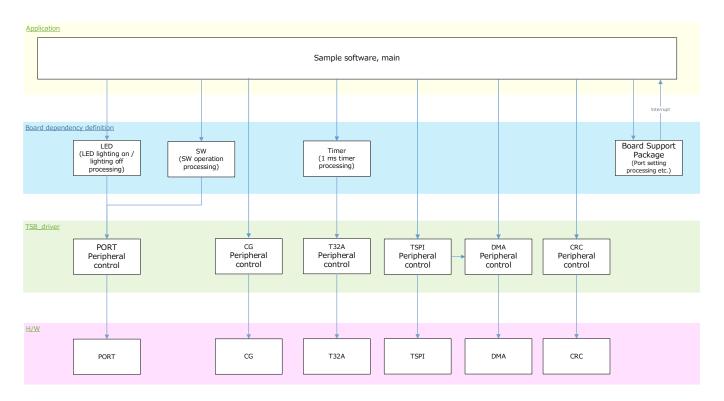
Document	Notes
Data sheet	Refer to the data sheet of MCU to be used.
Reference manual	Refer to the reference manual of each IP to be used.
Application note MCU User Guide	Refer to the MCU user guide to be used.



## 4. Target Sample Program

Sample Program	Outline
TSPI_MASTER_RECEIVE	Sample program of SPI function (Master Receive)

# 5. Configuration Diagram





## 6. Sample Program:TSPI\_MASTER\_RECEIVE

This sample software that uses the Master receive processing function of the SPI communication function to enter the reception waiting state when the switch is pressed, and switches the LED turn on / turn off each time data receive is completed.

This sample software allows you to select FIFO\_MODE or DMA\_MODE.

#### 6.1. Outlines of Operation

Turns off BSP\_LED\_1, BSP\_LED\_3, and BSP\_LED\_4.

When BSP\_PSW\_1 is pressed, BSP\_LED\_3 and BSP\_LED\_4 are turned off and data for the data size is received. Switches the lighting status (turn on / turn off) of BSP\_LED\_1.

When an SPI read error occurs, BSP\_LED\_3 is turn on.

When CRC does not match, BSP\_LED\_4 is turn on.

#### 6.2. Function to Use

The functions to use are as follows:

For the Port assignment of each BSP channel, refer to the MCU user guide.

IP	Channel	Objective
TSPI	BSP_TSPI_1	SPI Communication
T32A	BSP_T32A_TIMER_1	Interval timer
PORT(Push-Switch)	BSP_PSW_1	Event Trigger
	BSP_LED_1	For operation check
PORT(LED)	BSP_LED_3	For operation check
	BSP_LED_4	For operation check

## 6.3. Interrupt to Use

Interrupt	Outlines
INTT32A00A	T32A Timer_A
	Timer counter increment every 1ms for SW processing
*1	SPI receive interrupt
*2	SPI error interrupt
INTDMAATC	DMA transmit end interrupt
INTDMAAERR	DMA error interrupt

<sup>\*1</sup> For SBK-M4KN, "INTSCORX", for AdBun-M3HQF10, "INTT1RX"

#### 6.4. Configuration

"main.c" configuration setting.

Configuration	Current Value	Description
DATA LENGTH	10	Data size (Unit: byte)
DATA_LENGTH	10	Set to 16 by setting the compile switch CHK_CODE.
CHK CODE	CHK CODE CRC16	CHK_CODE_CRC16 and CHK_CODE_CRC32 can be
CHK_CODE	CHK_CODE_CKC16	switched
RX_MODE	FIFO_MODE	FIFO_MODE and DMA_MODE can be switched
RX_FILL_LEVEL	4	Receive Fill level setting

#### 6.5. Example of Terminal Emulator Output

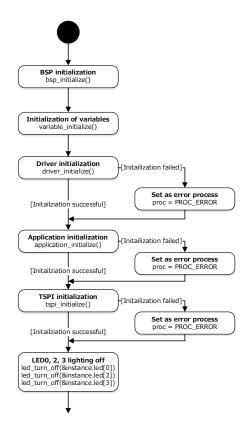
Nothing.

<sup>\*2</sup> For SBK-M4KN, "INTSC0ERR", for AdBun-M3HQF10, "INTT1ERR"

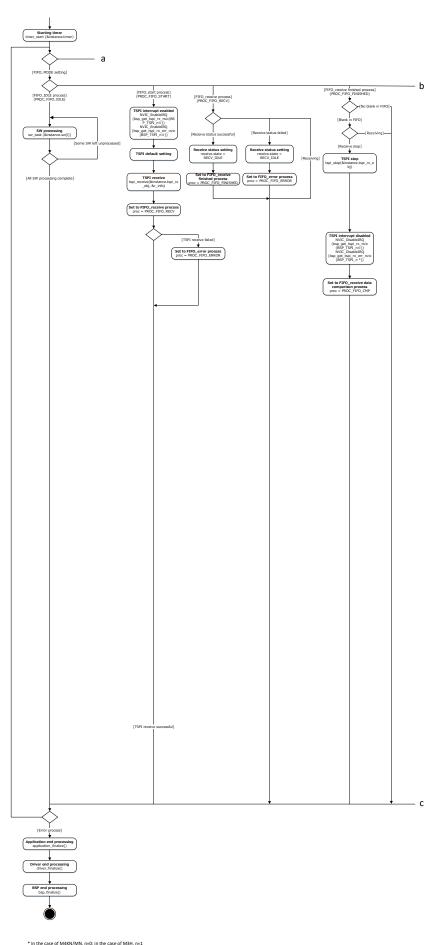


## 7. Activity diagram

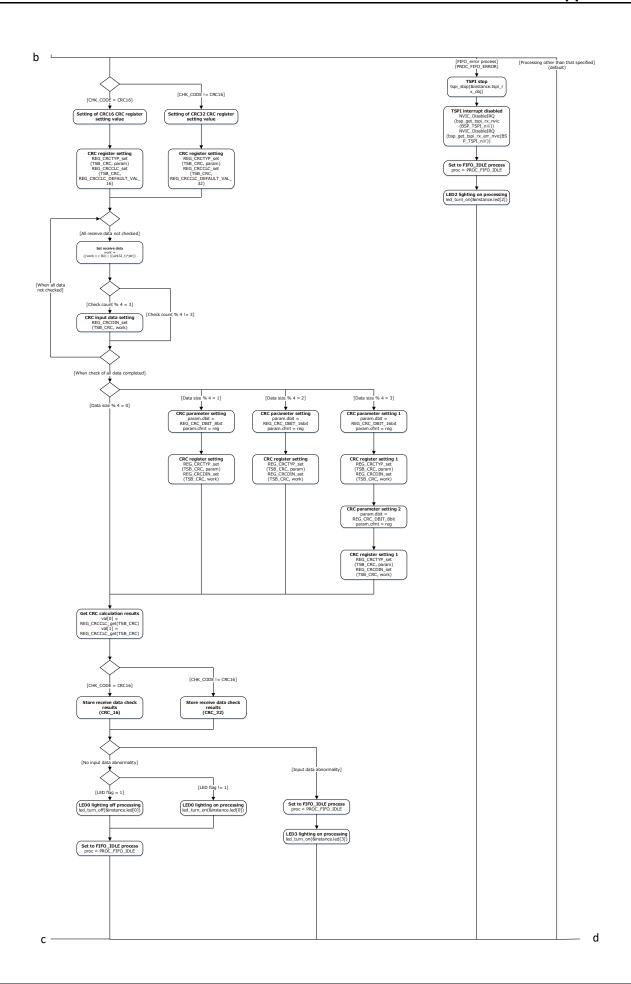
## 7.1. main



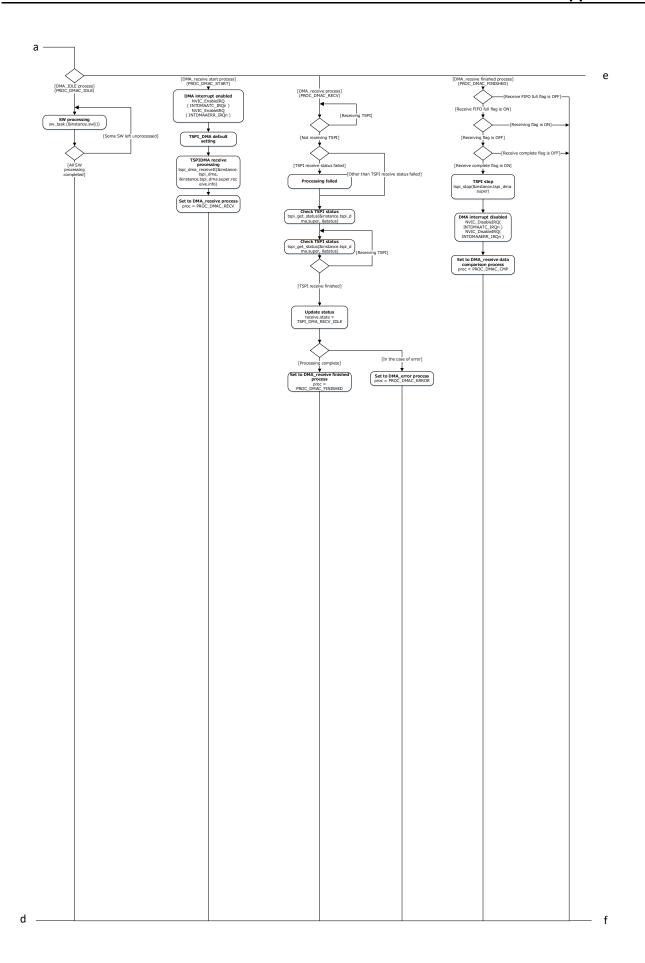




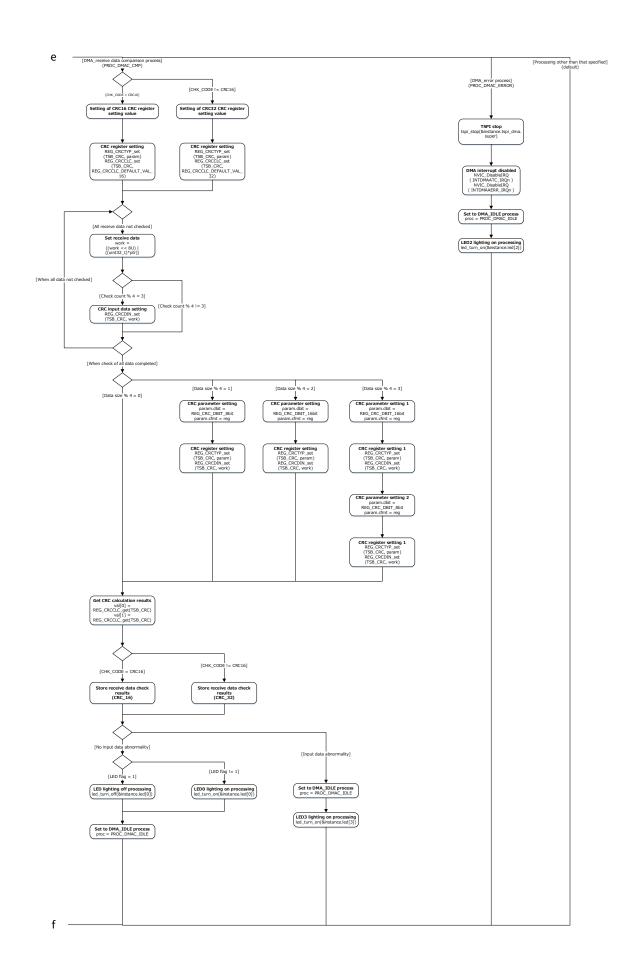






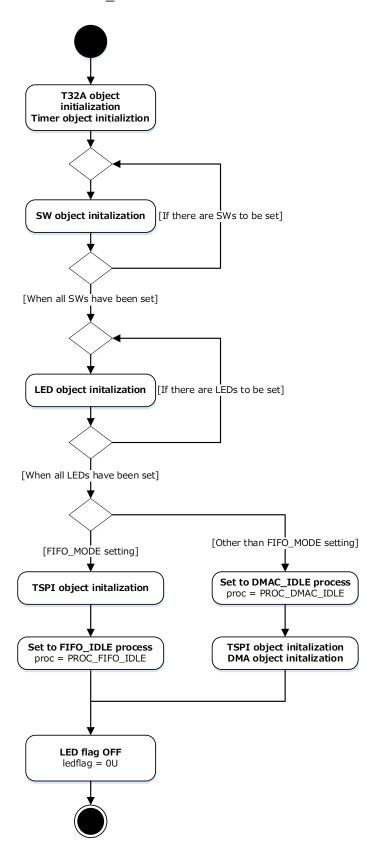






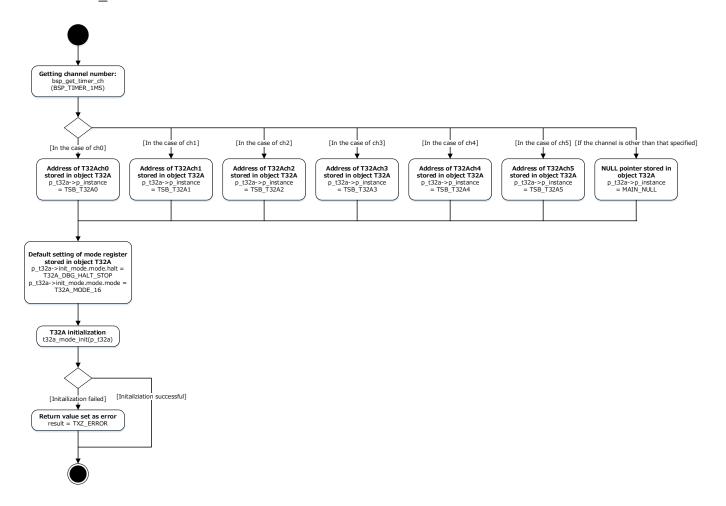


### 7.2. variable\_initalize

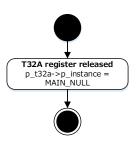




### 7.3. driver\_initialize

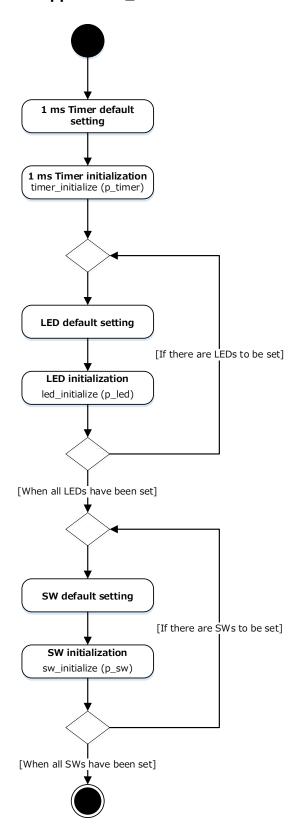


### 7.4. driver\_finalize



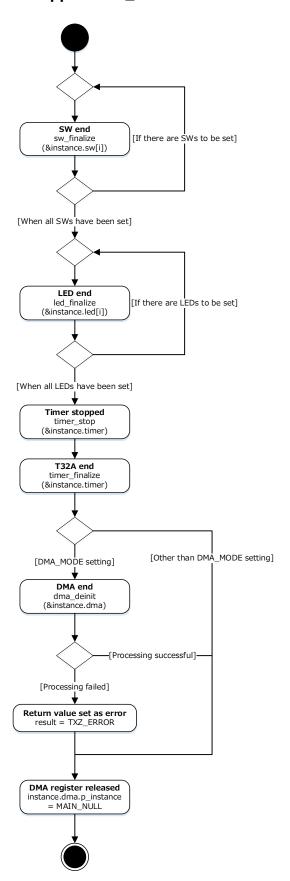


## 7.5. application\_initialize



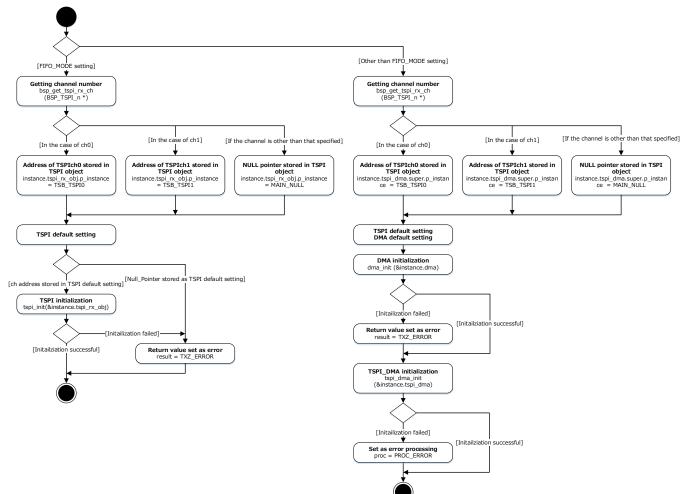


## 7.6. application\_finalize





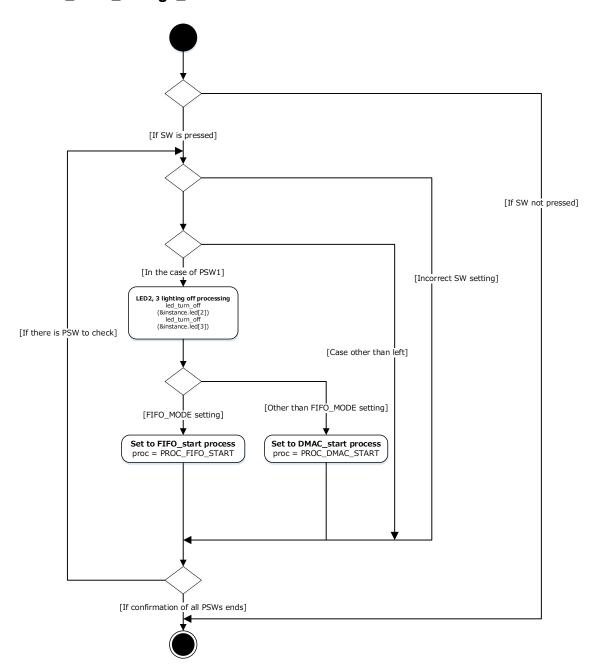
## 7.7. tspi\_initialize



\* In the case of M4KN/MN, n=0; in the case of M3H, n=1

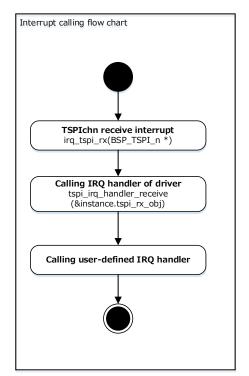


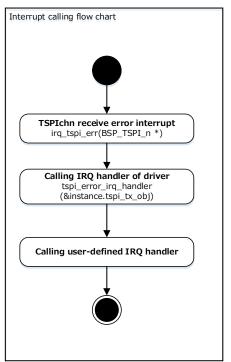
## 7.8. sw\_state\_change\_handler

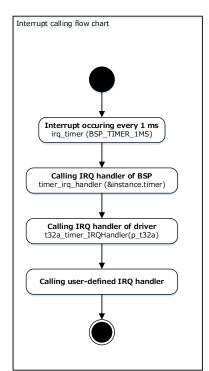


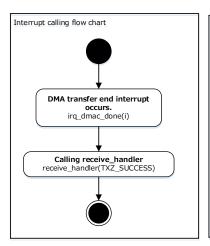


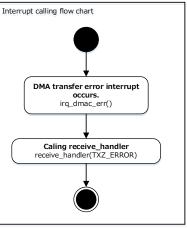
## 7.9. Interrupt



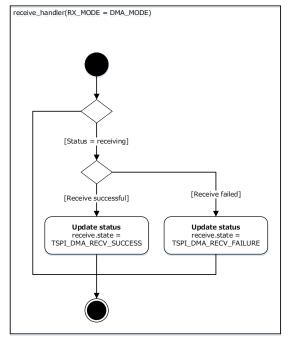




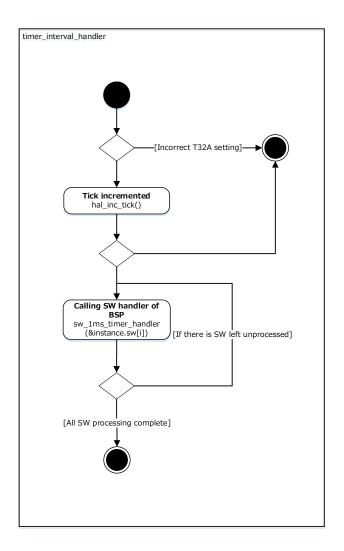


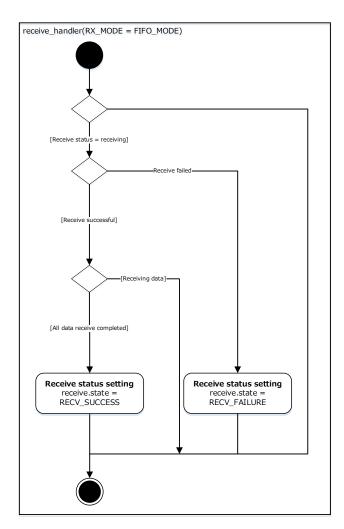


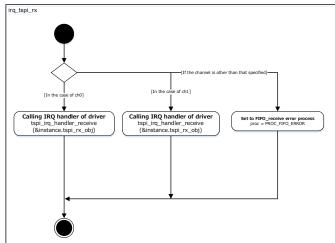
\* In the case of M4KN/MN, n=0; in the case of M3H, n=1

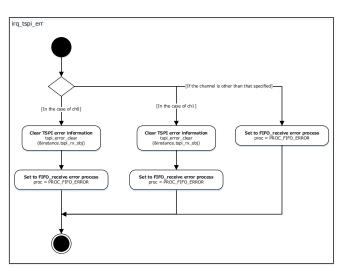














# 8. Revision History

Revision	Date	Description
1.0	2023-10-16	First release

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