# TBD62502A series, TBD62503A series Usage considerations

### **Function of transistor array**

There are various kinds of transistor arrays depending on their functions.

Input active level

There are two types. The TBD62502A series and the TBD62503A series are high active type.

Туре	Description	TBD62502A /TBD62503A series
High active	Output is ON by inputting "H" level to input pin	0
Low active	Output is ON by inputting "L" level to input pin	—

•Output clamp diode

There are two types. The TBD62502A series and the TBD62503A series are non built-in type.

Туре	Description	TBD62502A /TBD62503A series
Built-in	Best for the drive of the motor, the relay, and the solenoid. (Capable of driving the LED and the level shift circuit.)	—
Non Built-in	Best for the drive of the LED and the level shift circuit. (Incapable of driving the motor, the relay and the solenoid.)	0

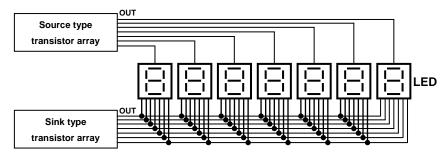
#### •Output current system

There are two types. The TBD62502A series and the TBD62503A series are sink type. Connecting point of each load is different.

Туре	Description	TBD62502A /TBD62503A series
Sink type	Output of current sink type (output pull) Power supply U U U U U U U U U U U U U U U U U U U	Ο
Source type	Output of current source type (output push) Power supply VCC Current	_

### Example of application

Dynamic drive control is possible by combining transistor arrays of the sink type and the source type.

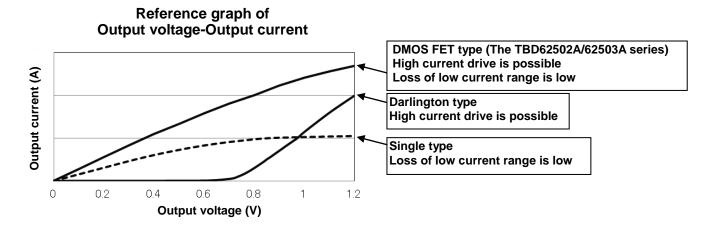


### •Construction of output circuit

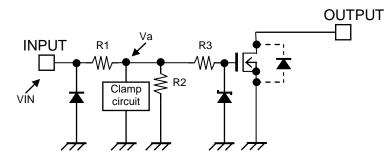
There are three types. The TBD62502A series and the TBD62503A series are DMOS FET type.

Туре	Description	TBD62502A /TBD62503A series
DMOS FET type	GND Features High current drive is possible Loss of low current range is low	Ο
Bipolar transistor Darlington type	GND Features High current drive is possible	_
Bipolar transistor Single type	GND OUT Features Loss of low current range is low	_

Reference: Characteristics graph (Feature of each type)



## TOSHIBA Basic circuit



- \* TBD62503A series internal resistance : R1=11kΩ(typ.), R2=33kΩ(typ.), R2=6kΩ(typ.)
- \* TBD62502A series internal resistance : R1=16.5k $\Omega$ (typ.), R2=8k $\Omega$ (typ.), R2=6k $\Omega$ (typ.)
- $^{\ast}$  The accuracy of the internal resistance are ± 30% (reference value).
- \* The operation of the clamp circuit

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	Product	Condition	Voltage of Va
		(1) = (1) + (1) + (1) = (1)	The clamp circuit controls the upper limit of
	TBD62503A series	VIN>4V(typ.)	Va. The upper limit of the Va is about 4V.
		VIN<11V(typ.)	about 0V
	TBD62502A series	VIN≥11V(typ.)	The clamp circuit controls the upper limit of
			Va. The upper limit of the Va is about 4V.

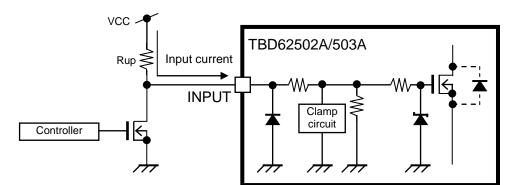
Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

#### Control of output ON/OFF

Outputs of the TBD62502A series and the TBD62503A series are constructed by DMOS FET. ON/OFF of output is controlled according to the level of applied voltage to the input pin.

Product	VIN(ON)	VIN(OFF)
TBD62502A series	14V to 25V	0V to 7.0V
TBD62503A series	2.5V to 25V	0V to 0.6V

In case the voltage is inputted through the pull up resistance externally, confirm that it meets the condition of VIN (ON) on consideration of the voltage fall in the external resistance (Rup).



#### •Notes in usage

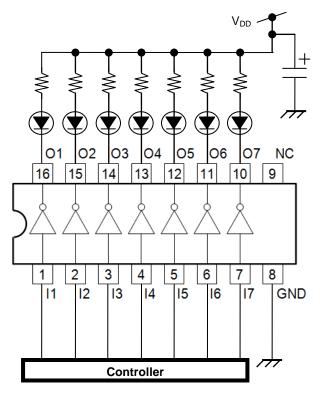
Following treatment for pins of unusage channels is recommended.

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Pin	Treatment
11,12,13,14,15,16,17	Output is off in the open state because input pin has pull down processing. However, it is recommended to connect to GND to avoid malfunction by noise.
01,02,03,04,05,06,07	Open or GND connection is recommended.

# Example of application circuit

•Drive LED

In case of driving 7 LEDs



## Loss calculation of the IC

In using the IC, take enough margins to configure by referring to the PD-Ta graph after calculating the loss of the IC from below formula. In the conditioning range of the PD-Ta graph, operating the IC at 250mA (max) per 1ch is possible.

### Loss calculation

 $PD@(W) = IOUT(A) \times IOUT(A) \times RON(\Omega) \times ONDuty \times Ch + VIN(V) \times IIN(A) \times ONDuty \times Ch$ 

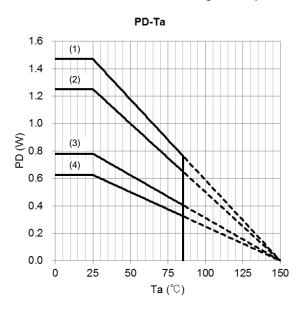
\* RON: Please refer to an electrical characteristic of a data seat. \*ONDuty: Apply ON term/cycle

However, when ON term is 25ms or more, apply 1 for ONDuty.

\*Ch: number of driving channels.

### •PD-Ta graph

Conditions: Absolute maximum rating of the junction temperature (Tj) is 150°C.



(1)	PG type alone	

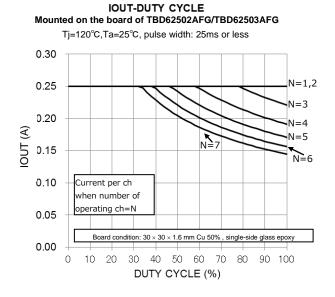
- (2) When mounted on FWG type,
- JEDEC 2s2p When mounted on FNG type
- (3)
- $(50 \times 50 \times 1.6 \text{ mm Cu } 40\%, \text{ single-side glass epoxy})$ (4) When mounted on FG type  $(30 \times 30 \times 1.6 \text{ mm Cu } 50\%, \text{ single-side glass epoxy})$

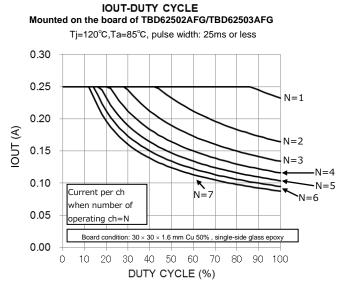
### Thermal resistance

PG type	: Rth(j-a) =85°C/W(alone)
FG type	: Rth(j-a) =200°C/W(30 × 30 × 1.6 mm Cu 50% single-side glass epoxy)
FNG type	: Rth(j-a) =160°C/W(50 × 50 × 1.6 mm Cu 40% single-side glass epoxy)
FWG type	: Rth(j-a) =100°C/W(JEDEC 2s2p)

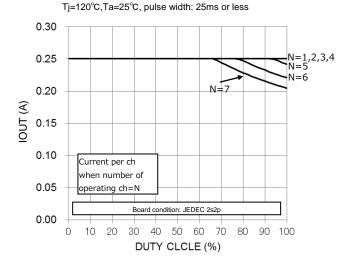
### **Reference data**

\*The data is for reference, not guaranteed.



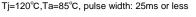


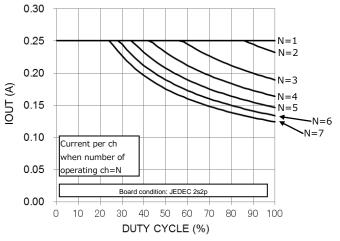
IOUT-DUTY CYCLE Mounted on the board of TBD62502AFWG/TBD62503AFWG



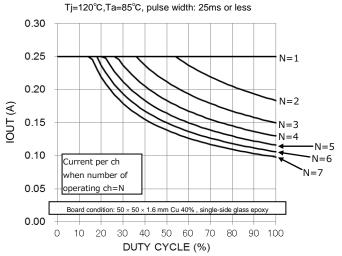
IOUT-DUTY CYCLE Mounted on the board of TBD62502AFNG/TBD62503AFNG Tj=120°C,Ta=25°C, pulse width: 25ms or less 0.30 N=1,2 0.25 N=3 N=40.20 N=5 IOUT (A) N=6 N=7 0.15 0.10 Current per ch when number of operating ch=N 0.05 rd condition:  $50 \times 50 \times 1.6$  mm Cu 40% , single-side glass epoxy 0.00 10 20 30 40 50 60 70 80 90 100 DUTY CYCLE (%)

IOUT-DUTY CYCLE Mounted on the board of TBD62502AFWG/TBD62503AFWG

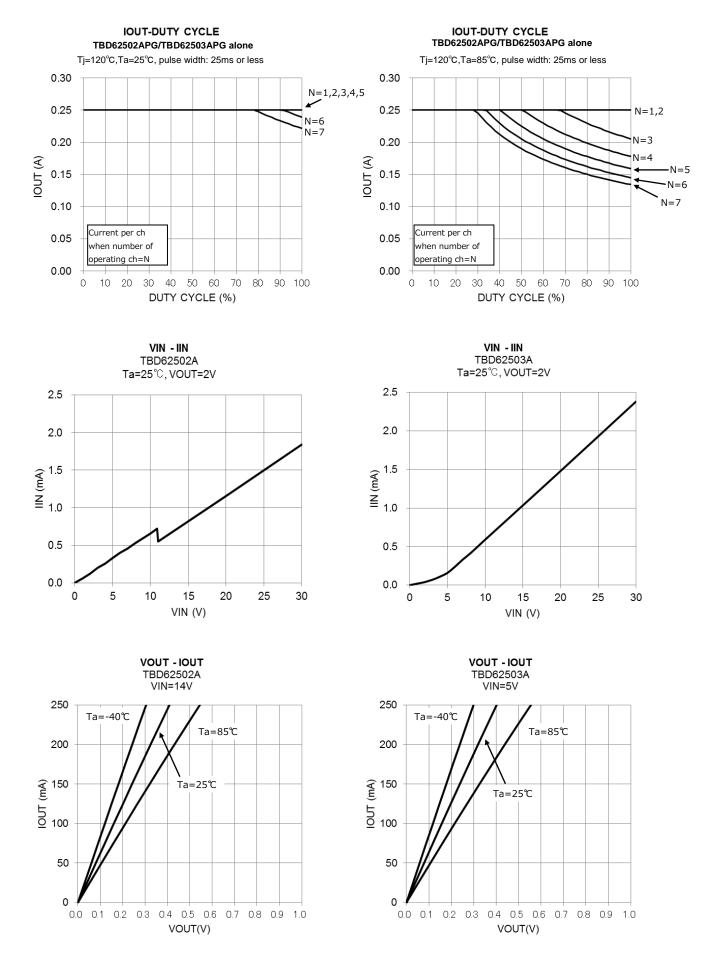




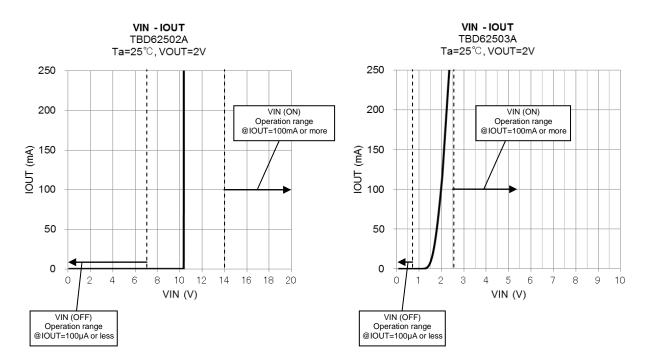
IOUT-DUTY CYCLE Mounted on the board of TBD62502AFNG/TBD62503AFNG



\*The data is for reference, not guaranteed.

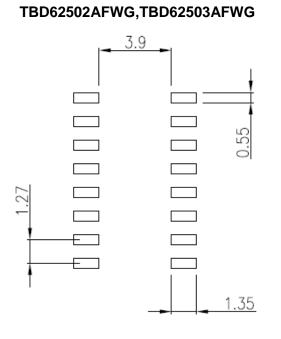


\*The data is for reference, not guaranteed.

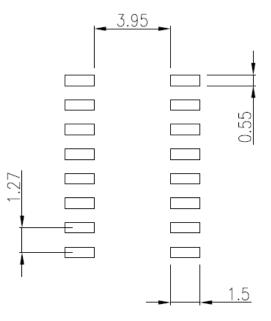


## Land pattern dimension (Reference)

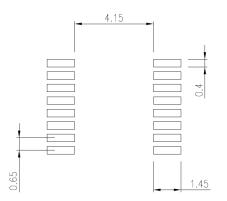
Unit: mm



### TBD62502AFG,TBD62503AFG



### TBD62502AFNG,TBD62503AFNG



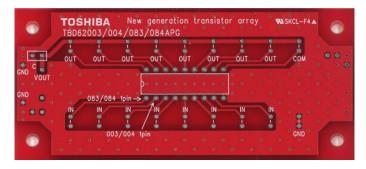
Notes

- All linear dimensions are given in millimeters unless otherwise specified.
- This drawing is based on JEITA ET-7501 Level3 and should be treated as a reference only.
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- •You are solely responsible for all aspects of your own land pattern, including but not limited to soldering processes.
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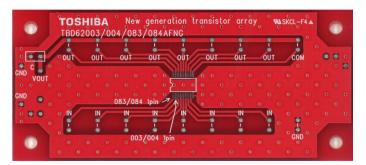
## **Evaluation board**

Drawing

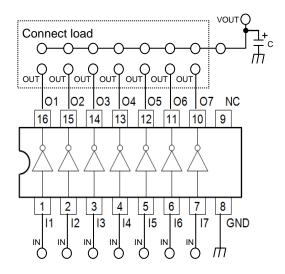
Evaluation board of the TBD62502APG and the TBD62503APG



Evaluation board of the TBD62502AFNG and the TBD62503AFNG



Circuit



### **Notes on Contents**

### **1. Pin Connection Diagrams**

The pin connection diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

### 2. Basic Circuits

The basic circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

#### 3. Test Circuits

The test circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

#### 4. Timing Charts

Timing charts may be simplified or some parts of them may be omitted for explanatory purposes.

### IC Usage Considerations Notes on handling of ICs

[1] The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.

Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.

[2] Do not insert devices in the wrong orientation or incorrectly.

Make sure that the positive and negative terminals of power supplies are connected properly.

Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.

In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.

- [3] Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- [4] If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.

Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.

[5] Carefully select external components (such as inputs and negative feedback capacitors) and load components (such as speakers), for example, power amp and regulator.

If there is a large amount of leakage current such as input or negative feedback condenser, the IC output DC voltage will increase. If this output voltage is connected to a speaker with low input withstand voltage, overcurrent or IC failure can cause smoke or ignition. (The over current can cause smoke or ignition from the IC itself.) In particular, please pay attention when using a Bridge Tied Load (BTL) connection type IC that inputs output DC voltage to a speaker directly.

### Points to remember on handling of ICs

Heat Radiation Design

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature  $(T_j)$  at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into considerate the effect of IC heat radiation with peripheral components.

Back-EMF

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond absolute maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

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